Variational Bayesian inference for agent-based models

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> INET Seminar 23rd Nov 2023





Gradient-Assisted Calibration for Financial Agent-Based Models

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Forthcoming in:

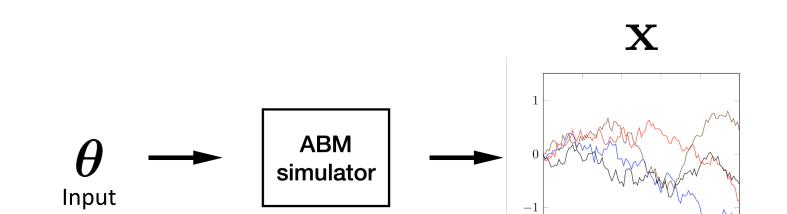
Proceedings of the Fourth International Conference on AI in Finance (ICAIF 2023)

GitHub repo: joelnmdyer/gradient_assisted_calibration_abm





Introduction



ABM simulator

parameters

• (Stochastic) simulation model of many autonomous, interacting agents making (often discrete) decisions

Generated data

40

60

100

 Simulation denoted mathematically as sampling from likelihood function:

$$\mathbf{x} \sim p(\mathbf{x} \mid \boldsymbol{\theta})$$





Using agent-based models

 Usually want to calibrate ABMs when applying them in practice, e.g. using Bayesian inference:

$$\pi(m{ heta} \mid \mathbf{y}) \propto e^{-\ell(m{ heta},\mathbf{y})}\pi(m{ heta})$$
Observed data
 $\mathbf{y} \longmapsto m{ heta}$

 Calibration (and other problems) made complicated by complexity of ABMs – likelihood function unavailable, expensive to simulate, discrete randomness prevents immediate construction of useful gradients etc.





This talk

- Performing optimisation-centric calibration procedures with and without model gradients
- How to get around difficulty of differentiating through discrete randomness





$$\pi(\boldsymbol{\theta} \mid \mathbf{y}) \propto e^{-\ell(\boldsymbol{\theta}, \mathbf{y})} \pi(\boldsymbol{\theta})$$





$$\pi(\boldsymbol{\theta} \mid \mathbf{y}) = \frac{e^{-\ell(\boldsymbol{\theta}, \mathbf{y})}}{Z(\mathbf{y})} \pi(\boldsymbol{\theta})$$





$$\pi(\boldsymbol{\theta} \mid \mathbf{y}) = \frac{e^{-\ell(\boldsymbol{\theta}, \mathbf{y})}}{Z(\mathbf{y})} \pi(\boldsymbol{\theta})$$

$$q^* = \arg\min_{q \in \mathcal{Q}} \mathbb{E}_{\boldsymbol{\theta} \sim q} \left[\log \frac{q(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta} \mid \mathbf{y})} \right]$$





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$$q^* = \arg\min_{q \in \mathcal{Q}} \mathbb{E}_{\boldsymbol{\theta} \sim q} \left[-\log \frac{e^{-\ell(\boldsymbol{\theta}, \mathbf{y})}}{Z(\mathbf{y})} + \log \frac{q(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta})} \right]$$





$$\pi(\boldsymbol{\theta} \mid \mathbf{y}) = \frac{e^{-\ell(\boldsymbol{\theta}, \mathbf{y})}}{Z(\mathbf{y})} \pi(\boldsymbol{\theta})$$

Taking \mathcal{Q} to be the set of all distributions on $\mathbf{\Theta}$:

$$q^* = \arg\min_{q \in \mathcal{Q}} \mathbb{E}_{\boldsymbol{\theta} \sim q} \left[\ell(\boldsymbol{\theta}, \, \mathbf{y}) + \log \frac{q(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta})} \right]$$





$$\pi(\boldsymbol{\theta} \mid \mathbf{y}) = \frac{e^{-\ell(\boldsymbol{\theta}, \mathbf{y})}}{Z(\mathbf{y})} \pi(\boldsymbol{\theta})$$

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$$q^*(\boldsymbol{\theta}) = \pi(\boldsymbol{\theta} \mid \mathbf{y})$$





$$\pi(\boldsymbol{\theta} \mid \mathbf{y}) = \frac{e^{-\ell(\boldsymbol{\theta}, \mathbf{y})}}{Z(\mathbf{y})} \pi(\boldsymbol{\theta})$$

Taking \mathcal{Q}_{Φ} to be a restricted set $\{q_{\phi} \mid \phi \in \Phi\}$ of distributions on Θ :

$$\phi^* = \arg\min_{\phi \in \Phi} \mathbb{E}_{\boldsymbol{\theta} \sim q_{\phi}} \left[\ell(\boldsymbol{\theta}, \mathbf{y}) + \log \frac{q_{\phi}(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta})} \right]$$

$$q_{\phi^*}(\boldsymbol{\theta}) \approx \pi(\boldsymbol{\theta} \mid \mathbf{y})$$





$$\pi(\boldsymbol{\theta} \mid \mathbf{y}) = \frac{e^{-\ell(\boldsymbol{\theta}, \mathbf{y})}}{Z(\mathbf{y})} \pi(\boldsymbol{\theta})$$

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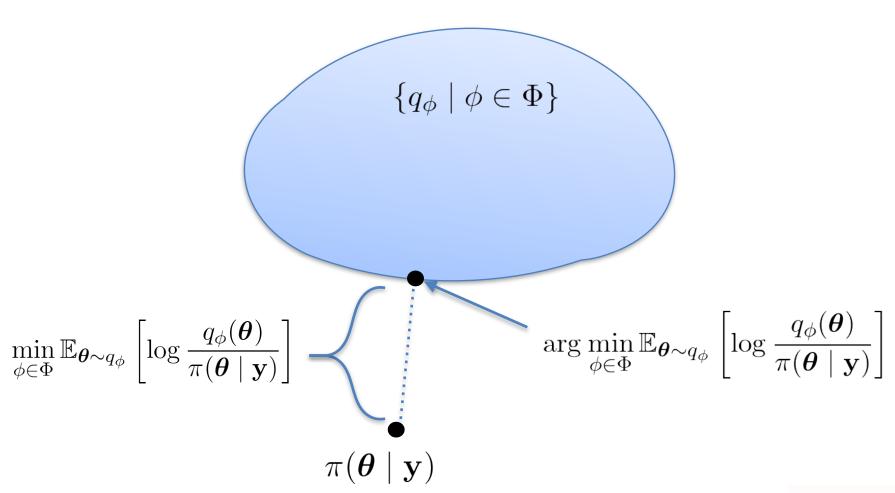
$$q_{\phi^*}(\boldsymbol{\theta}) \approx \pi(\boldsymbol{\theta} \mid \mathbf{y})$$

Generalised variational Bayesian inference





Quick schematic of variational Bayes







Optimisation problem:

$$\min_{\phi \in \Phi} \mathbb{E}_{\boldsymbol{\theta} \sim q_{\phi}} \left[\log \frac{q_{\phi}(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta} \mid \mathbf{y})} \right]$$



Optimisation problem:

$$\min_{\phi \in \Phi} \mathbb{E}_{\boldsymbol{\theta} \sim q_{\phi}} \left[\log \frac{q_{\phi}(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta} \mid \mathbf{y})} \right]$$

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Optimisation problem:

$$\min_{\phi \in \Phi} \mathbb{E}_{\boldsymbol{\theta} \sim q_{\phi}} \left[\log \frac{q_{\phi}(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta} \mid \mathbf{y})} \right]$$

?
$$\nabla_{\phi} \mathbb{E}_{\boldsymbol{\theta} \sim q_{\phi}} \left| \ell(\boldsymbol{\theta}, \mathbf{y}) + \log \frac{q_{\phi}(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta})} \right|$$
 ?





Optimisation problem:

$$\min_{\phi \in \Phi} \mathbb{E}_{\boldsymbol{\theta} \sim q_{\phi}} \left[\log \frac{q_{\phi}(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta} \mid \mathbf{y})} \right]$$

Find G such that
$$\mathbb{E}[G] = \nabla_{\phi} \mathbb{E}_{\boldsymbol{\theta} \sim q_{\phi}} \left[\ell(\boldsymbol{\theta}, \mathbf{y}) + \log \frac{q_{\phi}(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta})} \right]$$





G such that
$$\mathbb{E}[G] = \nabla_{\omega} \mathbb{E}_{z \sim p_{\omega}} [\mathcal{L}(z)]$$





G such that
$$\mathbb{E}[G] = \nabla_{\omega} \mathbb{E}_{z \sim p_{\omega}} [\mathcal{L}(z)]$$

Score-based estimator

$$G = \mathcal{L}(z)\nabla_{\omega}\log p_{\omega}(z)$$

$$\mathbb{E}_{z \sim p_{\omega}} \left[\mathcal{L}(z) \nabla_{\omega} \log p_{\omega}(z) \right] = \nabla_{\omega} \mathbb{E}_{z \sim p_{\omega}} \left[\mathcal{L}(z) \right]$$





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- Generically applicable (e.g. in presence of discrete randomness)
- Can be high-variance less reliable gradients





$$G$$
 such that $\mathbb{E}[G] = \nabla_{\omega} \mathbb{E}_{z \sim p_{\omega}} [\mathcal{L}(z)]$

Pathwise estimator

$$G = \nabla_{\omega} \mathcal{L}(g(u, \omega))|_{g(u, \omega) = z}$$

$$\mathbb{E}_{u \sim p} \left[\nabla_{\omega} \mathcal{L}(g(u, \omega)) \big|_{g(u, \omega) = z} \right] = \nabla_{\omega} \mathbb{E}_{z \sim p_{\omega}} \left[\mathcal{L}(z) \right]$$





$$G$$
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- Requires differentiable $\mathcal L$ & "reparameterisable" $\mathcal Z$
- Is often (though not always) *lower-variance* often gives more informative gradients!





A possible benefit of differentiability

Find G such that
$$\mathbb{E}[G] = \nabla_{\phi} \mathbb{E}_{\boldsymbol{\theta} \sim q_{\phi}} \left[\ell(\boldsymbol{\theta}, \mathbf{y}) + \log \frac{q_{\phi}(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta})} \right]$$





A possible benefit of differentiability

Minimise with gradient-based descent methods:

Find G such that
$$\mathbb{E}[G] = \nabla_{\phi} \mathbb{E}_{\boldsymbol{\theta} \sim q_{\phi}} \left[\ell(\boldsymbol{\theta}, \mathbf{y}) + \log \frac{q_{\phi}(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta})} \right]$$

If our choice of $\ell(\boldsymbol{\theta}, \mathbf{y})$ is (a) differentiable and (b) estimated using samples from the agent-based model, then we can *potentially* obtain lower-variance estimates of the gradient during optimisation by implementing the agent-based model in a differentiable programming language and using the *pathwise* gradient estimator





Reparameterisable sampling





Reparameterisable sampling

$$z \sim \mathcal{N}(\mu, \sigma)$$





Reparameterisable sampling

$$u \sim \mathcal{N}(0,1)$$

 $z = g(u,\omega),$
where $\omega = (\mu,\sigma)$ and $g(u,\omega) = \mu + \sigma u$

$$z \sim \mathcal{N}(\mu, \sigma)$$

or





Reparameterisable sampling

$$z \sim \mathcal{N}(\mu, \sigma)$$
 or

$$u \sim \mathcal{N}(0,1)$$

 $z = g(u,\omega),$
where $\omega = (\mu,\sigma)$ and $g(u,\omega) = \mu + \sigma u$

Reparameterisation





or

Reparameterisable sampling

$$z \sim \mathcal{N}(\mu, \sigma)$$

$$u \sim \mathcal{N}(0,1)$$

$$z = g(u,\omega),$$
 where $\omega = (\mu,\sigma)$ and

Reparameterisation

 $g(u,\omega) = \mu + \sigma u$

$$\frac{\partial z}{\partial \mu} = 1; \quad \frac{\partial z}{\partial \sigma} = u$$





Reparameterisable sampling for discrete random variables

- Harder, but possible:
 - Approximate model gradient using smoothed versions of discrete random variables (e.g. Gumbel-Softmax [1])
 - Imperfect solution/workaround, since the model gradient is still not "correct". But can work sufficiently well in some settings!
 - StochasticAD [2]

[1] Eric Jang, Shixiang Gu, and Ben Poole. 2017. Categorical Reparameterization with Gumbel-Softmax. arXiv:1611.01144 [cs, stat]

[2] Gaurav Arya, Moritz Schauer, Frank Schäfer, and Chris Rackauckas. 2022. Automatic Differentiation of Programs with Discrete Randomness. arXiv:2210.08572 [cs, math]





Overall strategy

- 1. Implement ABM in differentiable framework (e.g. PyTorch, Jax)
- 2. Use aforementioned tricks to obtain an (approximate) model gradient (without changing the forward pass of model!)









Agent-based model

Implement and calibrate differentiable version of simple ABM of volatility clustering in financial markets (Cont, 2007)

- Discrete choices by agents
- Threshold effects



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Simulation loop:

- 1. Each agent receives a common information signal
- 2. Each agent processes signal and decides whether to place purchase order
- 3. Excess demand determines change in price
- 4. Agents consequently update their signal processing procedure





Inference problem

Perform generalised Bayesian inference targeting

$$\pi(\boldsymbol{\theta} \mid \mathbf{y}) \propto e^{-\ell(\boldsymbol{\theta}, \mathbf{y})} \pi(\boldsymbol{\theta})$$

with $\ell(\theta, y)$ a divergence between distribution of simulated and "real" log-returns, by solving minimisation problem shown before



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Approximate (intractable) $\pi(\boldsymbol{\theta} \mid \mathbf{y})$ using variational inference

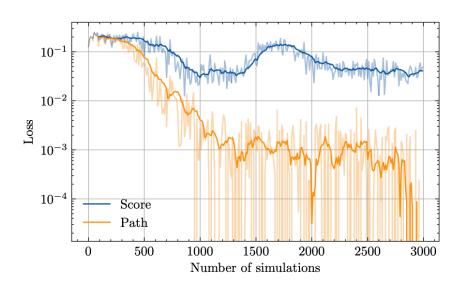
$$\min_{\phi \in \Phi} \mathbb{E}_{\boldsymbol{\theta} \sim q_{\phi}} \left[\ell(\boldsymbol{\theta}, \mathbf{y}) + \log \frac{q_{\phi}(\boldsymbol{\theta})}{\pi(\boldsymbol{\theta})} \right]$$

taking q_{ϕ} to be a "normalising flow" (i.e. neural density estimator)





Calibrate using our BlackBIRDS* software package



 S_t 10^0 S_t 10^{-1} Predicted (score)

Predicted (path)

True

0 20 40 60 80 100

Figure 1: Training loss for the generalised variational inference scheme with score-based (blue) and pathwise (orange) gradient estimators. Dark lines show the moving average loss by averaging over 10 epochs.

Figure 3: Sample trajectories for the asset price from the posterior predictive distributions obtained from the score-based (blue) and pathwise (orange) gradient estimators. True asset price is shown with the black line.





Code?



joelnmdyer / gradient_assisted_calibration_abm



arnauqb Arnau Quera-Bofarull

joelnmdyer Joel Dyer

Recently published in: The Journal of Open Source Software





Summary/discussion

- Bayesian inference (and other calibration approaches) for ABMs can be written as an optimisation problem – minimising expectations of random losses
- Differentiability of ABMs can sometimes help to perform this optimisation
- Limitations:
 - Usefulness of gradients depends on bias-variance tradeoff of estimators they are used for
 - Simulator gradients less useful when (derivative of) loss function is intractable (consider e.g. maximum likelihood estimation)





Summary/discussion

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Thank you!

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